

「R」におけるGWRモデルの係数推定法

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1 GWRモデル

地理的加重回帰モデル(以後GWRモデル)とは、 x と y の関係自体が空間的に変動していると考えたモデルであり回帰係数 β_0, β_1 が地区ごとに変動する。地区 i のパラメータ β_{0i}, β_{1i} を推定するとき

$$W_i y = W_i X \beta_i + \epsilon \quad (1)$$

ここに

$$W_i = \text{diag}(h_{i1}, h_{i2}, \dots, h_{ij})$$
$$\beta_i = (\beta_{0i} \ \beta_{1i})^T$$

パラメータ β_i は重み付け最小二乗法を解くことによって求める。地区 i を推定する際の重み付け最小二乗法は

$$\min \left[\sum_{j=1}^n \{y_j - (\beta_{0i} + \beta_{1i} x_j)\}^2 h_{ij}^2 \right]$$

となり、推定パラメータは

$$\hat{\beta}_i = (X^t W_i X)^{-1} (X^t W_i Y) \quad (2)$$

2 「R」の推定方法

Rのパッケージ「spgwr」に関数「gwr」があり、引数に最適バンド幅、座標情報の入った行列を入力すると、式(2)を計算する。「gwr」の中身の一部を下に示す。

```
1  mt <- terms(formula, data = data)
2  mf <- lm(formula, data, method = "model.frame", na.action = na.fail)
3  lm <- lm(formula, data, x = TRUE, y = TRUE)
4  n <- NROW(fit.points)
5  if (is.null(colnames(fit.points)))
6    colnames(fit.points) <- c("x", "y")
7  y <- model.extract(mf, "response")
8  x <- model.matrix(mt, mf)
9  m <- NCOL(x)
10 gwr.b <- matrix(nrow = n, ncol = m)
11 gwr.se <- matrix(nrow = n, ncol = m)
12 gwr.R2 <- numeric(n)
13 gwr.e <- numeric(n)
14 yiybar <- (y - mean(y))
15 colnames(gwr.b) <- colnames(x)
16 sum.w <- numeric(n)
17 for (i in 1:n) {
18   dxs <- spDistsN1(coords, fit.points[i, ], longlat = longlat)
19   if (any(!is.finite(dxs)))
20     dxs[which(!is.finite(dxs))] <- 0
21   w.i <- gweight(dxs^2, bandwidth[i])
22   if (any(w.i < 0 | is.na(w.i)))
23     stop(paste("Invalid weights for i:", i))
24   lm.i <- lm.wfit(y = y, x = x, w = w.i)
25   sum.w[i] <- sum(w.i)
26   gwr.b[i, ] <- coefficients(lm.i)
27   ei <- residuals(lm.i)
28   gwr.e[i] <- ei[i]
29   rss <- sum(ei * w.i * ei)
30   gwr.R2[i] <- 1 - (rss/sum(yiybar * w.i * yiybar))
31   p <- lm.i$rank
32   p1 <- 1:p
33   inv.Z <- chol2inv(lm.i$qr$qr[p1, p1, drop = FALSE])
34   gwr.se[i, ] <- sqrt(diag(inv.Z) * (rss/(n - p)))
35   if (!fp.given && hatmatrix)
36     lhat[i, ] <- t(x[i, ]) %*% inv.Z %*% t(x) %*% diag(w.i)
37 }$
```

GWRモデルを推定しているのは「lm.wfit」(package:stats)であることが分かる。「lm.wfit」とはどのような関数なのか、中身を以下に示す。

```
1   wts <- sqrt(w)
2   z <- .Fortran("dqrls", qr = x * wts, n = n, p = p, y = y *
3       wts, ny = ny, tol = as.double(tol), coefficients = mat.or.vec(p,
4       ny), residuals = y, effects = mat.or.vec(n, ny), rank = integer(1),
5       pivot = 1:p, qraux = double(p), work = double(2 * p),
6       PACKAGE = "base")
7   coef <- z$coefficients
8   pivot <- z$pivot
9   r1 <- seq_len(z$rank)
10  dn <- colnames(x)
11  z$coefficients <- coef
12  z$residuals <- z$residuals/wts
13  z$fitted.values <- y - z$residuals
14  z$weights <- w
$
```

計算に Fortran のプログラム「"dqrls"」(package:base) を用いていることが分かる。「dqrls」のある場所は、R のソースの、「/src/appl」にある「dqrls.f」である。

```

c
c   dqrdc uses householder transformations to compute the qr
c   factorization of an n by p matrix x.  column pivoting
c   based on the 2-norms of the reduced columns may be
c   performed at the users option.
c
c   on entry
c
c       x       double precision(ldx,p), where ldx .ge. n.
c               x contains the matrix whose decomposition is to be
c               computed.
c
c       ldx     integer.
c               ldx is the leading dimension of the array x.
c
c       n       integer.
c               n is the number of rows of the matrix x.
c
c       p       integer.
c               p is the number of columns of the matrix x.
c
c       jpvt    integer(p).
c               jpvt contains integers that control the selection
c               of the pivot columns.  the k-th column x(k) of x
c               is placed in one of three classes according to the
c               value of jpvt(k).
c
c               if jpvt(k) .gt. 0, then x(k) is an initial
c                   column.
c
c               if jpvt(k) .eq. 0, then x(k) is a free column.
c
c               if jpvt(k) .lt. 0, then x(k) is a final column.
c
c               before the decomposition is computed, initial columns
c               are moved to the beginning of the array x and final
c               columns to the end.  both initial and final columns
c               are frozen in place during the computation and only
c               free columns are moved.  at the k-th stage of the
c               reduction, if x(k) is occupied by a free column
c               it is interchanged with the free column of largest

```

```

c          reduced norm.  jpvt is not referenced if
c          job .eq. 0.
c
c      work  double precision(p).
c          work is a work array.  work is not referenced if
c          job .eq. 0.
c
c      job   integer.
c          job is an integer that initiates column pivoting.
c          if job .eq. 0, no pivoting is done.
c          if job .ne. 0, pivoting is done.
c
c      on return
c
c      x     x contains in its upper triangle the upper
c          triangular matrix r of the qr factorization.
c          below its diagonal x contains information from
c          which the orthogonal part of the decomposition
c          can be recovered.  note that if pivoting has
c          been requested, the decomposition is not that
c          of the original matrix x but that of x
c          with its columns permuted as described by jpvt.
c
c      qraux double precision(p).
c          qraux contains further information required to recover
c          the orthogonal part of the decomposition.
c
c      jpvt  jpvt(k) contains the index of the column of the
c          original matrix that has been interchanged into
c          the k-th column, if pivoting was requested.
c
c      linpack. this version dated 08/14/78 .
c      g.w. stewart, university of maryland, argonne national lab.
c
c      dqrdc uses the following functions and subprograms.
c
c      blas daxpy,ddot,dscal,dswap,dnrm2
c      fortran dabs,dmax1,min0,dsqrt
c
c      subroutine dqrdc(x,ldx,n,p,qraux,jpvt,work,job)
c      integer ldx,n,p,job

```

```

integer jpvt(*)
double precision x(ldx,*),qraux(*),work(*)
c
c internal variables
c
integer j,jp,jj, l,lp1,lup,maxj,pl,pu
double precision maxnrm,dnrm2,tt
double precision ddot,nrmxl,t
logical negj,swapj
c
c
pl = 1
pu = 0
if (job .eq. 0) go to 60
c
c pivoting has been requested. rearrange the columns
c according to jpvt.
c
do 20 j = 1, p
  swapj = jpvt(j) .gt. 0
  negj = jpvt(j) .lt. 0
  jpvt(j) = j
  if (negj) jpvt(j) = -j
  if (.not.swapj) go to 10
    if (j .ne. pl) call dswap(n,x(1,pl),1,x(1,j),1)
    jpvt(j) = jpvt(pl)
    jpvt(pl) = j
    pl = pl + 1
10  continue
20  continue
pu = p
do 50 jj = 1, p
  j = p - jj + 1
  if (jpvt(j) .ge. 0) go to 40
    jpvt(j) = -jpvt(j)
  if (j .eq. pu) go to 30
    call dswap(n,x(1,pu),1,x(1,j),1)
    jp = jpvt(pu)
    jpvt(pu) = jpvt(j)
    jpvt(j) = jp
30  continue

```

```

        pu = pu - 1
40      continue
50      continue
60      continue
c
c      compute the norms of the free columns.
c
      if (pu .lt. pl) go to 80
      do 70 j = pl, pu
          qraux(j) = dnorm2(n,x(1,j),1)
          work(j) = qraux(j)
70      continue
80      continue
c
c      perform the householder reduction of x.
c
      lup = min0(n,p)
      do 200 l = 1, lup
          if (l .lt. pl .or. l .ge. pu) go to 120
c
c          locate the column of largest norm and bring it
c          into the pivot position.
c
          maxnorm = 0.0d0
          maxj = l
          do 100 j = l, pu
              if (qraux(j) .le. maxnorm) go to 90
                  maxnorm = qraux(j)
                  maxj = j
90          continue
100         continue
          if (maxj .eq. l) go to 110
          call dswap(n,x(1,l),1,x(1,maxj),1)
          qraux(maxj) = qraux(l)
          work(maxj) = work(l)
          jp = jpvt(maxj)
          jpvt(maxj) = jpvt(l)
          jpvt(l) = jp
110         continue
120         continue
          qraux(l) = 0.0d0

```

```

        if (l .eq. n) go to 190
c
c        compute the householder transformation for column l.
c
        nrmxl = dnorm2(n-l+1,x(l,l),1)
        if (nrmxl .eq. 0.0d0) go to 180
            if (x(l,l) .ne. 0.0d0) nrmxl = dsign(nrmxl,x(l,l))
            call dscal(n-l+1,1.0d0/nrmxl,x(l,l),1)
            x(l,l) = 1.0d0 + x(l,l)
c
c        apply the transformation to the remaining columns,
c        updating the norms.
c
        lp1 = l + 1
        if (p .lt. lp1) go to 170
        do 160 j = lp1, p
            t = -ddot(n-l+1,x(l,l),1,x(l,j),1)/x(l,l)
            call daxpy(n-l+1,t,x(l,l),1,x(l,j),1)
            if (j .lt. pl .or. j .gt. pu) go to 150
            if (qraux(j) .eq. 0.0d0) go to 150
                tt = 1.0d0 - (dabs(x(l,j))/qraux(j))**2
                tt = dmax1(tt,0.0d0)
                t = tt
                tt = 1.0d0 + 0.05d0*tt*(qraux(j)/work(j))**2
            if (tt .eq. 1.0d0) go to 130
                qraux(j) = qraux(j)*dsqrt(t)
            go to 140
130            continue
                qraux(j) = dnorm2(n-l,x(l+1,j),1)
                work(j) = qraux(j)
140            continue
150            continue
160            continue
170            continue
c
c        save the transformation.
c
        qraux(l) = x(l,l)
        x(l,l) = -nrmxl
180        continue
190        continue

```

```
200 continue
    return
end
```